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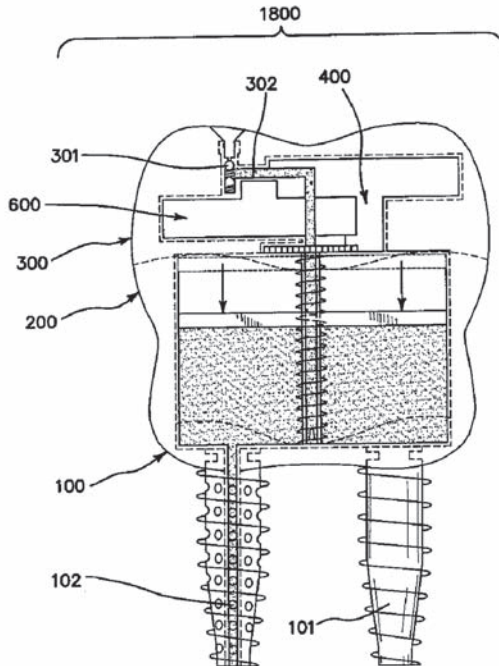
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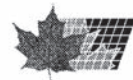
(54) Titre : APPAREIL MEDICATEUR POUR DENT ARTIFICIELLE, QUI PERMET DE CONTROLER, REGULER, CAPTER ET DIFFUSER DES AGENTS MEDICAUX DANS LE CORPS

(54) Title: AN ARTIFICIAL TOOTH MEDICATING APPARATUS FOR CONTROLLING, REGULATING, SENSING, AND RELEASING MEDICAL AGENTS INTO THE BODY



(57) Abrégé/Abstract:

An artificial tooth apparatus for dispensing medicating agents to the body through the patient's jaw bone comprising a mechanical movement and kinetic mainspring winder, a tourbillon mechanism, an electronic regulator, and a pump mechanism arranged and



(57) **Abbrégé(suite)/Abstract(continued):**

configured to allow any medicating agent to be dispensed from the apparatus in a highly controlled and regulated manner according to input received by the electronic regulator and the patient's specific pharmacokinetic and pharmacodynamic attributes. Multiple artificial teeth or a comprehensive bridge with several chambers may be used in cases where a polypharmaceutical approach is needed.

Abstract of the Disclosure

[0001] An artificial tooth apparatus for dispensing medicating agents to the body through the patient's jaw bone comprising a mechanical movement and kinetic mainspring winder, a tourbillon mechanism, a electronic regulator, and a pump mechanism arranged and configured to allow any medicating agent to be dispensed from the apparatus in a highly controlled and regulated manner according to input received by the electronic regulator and the patient's specific pharmacokinetic and pharmacodynamic attributes. Multiple artificial teeth or a comprehensive bridge with several chambers may be used in cases where a polypharmaceutical approach is needed.

We claim:

1. An implantable apparatus capable of delivering medicating agents to the body comprising:
 - a kinetic mainspring winder;
 - a mechanical movement coupled to and driven by the kinetic mainspring winder; and
 - a pump mechanism coupled to and driven by the mechanical movement, the pump mechanism delivering the medicating agents to the body at a time-measured rate.

2. The apparatus of claim 1 where the kinetic mainspring winder is an implant in a jaw bone.

3. The apparatus of claim 1 where energy supplied to the kinetic mainspring winder is obtained from movement of the jaw bone.

4. The apparatus of claim 1 where the pump mechanism comprises a refillable reservoir for holding a medicating agent.

5. The apparatus of claim 1 where the pump mechanism further comprises an implant screw with a perforated delivery duct coupled to the

apparatus for dispensing medicating agents into or near the adjacent blood vessels in the jaw bone.

6. The apparatus of claim 1 where the apparatus comprises a jaw implant, the jaw having a jaw plane and further comprising a means for positioning the rotor of the kinetic mainspring winder at a 5 degree inclination relative to the jaw plane.

7. The apparatus of claim 6 further comprising a timer and clutch mechanism coupled between the mechanical movement and the pump mechanism for selective dispensing the medicating agent into the body.

8. An implantable apparatus capable of delivering at least one medicating agent to the body comprising:

- a Faraday generator powered by jaw movements;
- a electrical power circuit coupled to the Faraday generator for storing electric energy generated by the Faraday generator;
- an electrically powered pump coupled to the electrical power circuit for delivering the medicating agents to the body;
- at least one sensor for providing a feedback signal related to the medicating agent; and

a regulator coupled to the electrical power circuit and coupled to and controlling the pump, the regulator coupled to the sensor and controlling the pump based on the feedback signal.

- 9.** The apparatus of claim **8** where the regulator comprises:
- a multiplexer;
 - a signal amplifier having an input coupled to the multiplexer;
 - an analog-to-digital converter having an input coupled to the signal amplifier;
 - a microcontroller having an input coupled to the analog-to-digital converter; and
 - a plurality of sensor elements coupled to the multiplexer including at least one of:
 - a free ion detector;
 - a pulse rate sensor;
 - a blood chemistry analyzer; or
 - a body temperature sensor.

- 10.** The apparatus of claim **9** further comprising a ROM, RAM, or NVM microchip or any combination thereof coupled to the microcontroller for the purposes of data storage.

11. The apparatus of claim **10** further comprising a kinetic mainspring winder powered by jaw movements that is coupled to the electrically powered circuit and to the electrically powered pump to provide energy for each.

12. A method for dispensing medicating agents into a body of a patient using an implant in a jaw bone of the patient comprising:
storing at least one medicating agent in the implant;
storing energy from normal jaw movements;
selectively converting the stored energy into controlled pumping of the at least one medicating agent stored in the implant in the jaw bone,; to selectively dispense the medicating agent stored in the implant into a blood flow path in the jaw bone at a controlled rate .

13. The method of claim **12** further comprising sensing at least one sensed biological input or user controlled input, and selectively controlling dispensing a medicating agent stored in the implant into the blood flow path in the jaw bone by at least one sensed biological input or user controlled input.

14. The method of claim **13** further comprising providing a plurality of implants in the jaw bone for a polypharmacy treatment thus allowing a combination of therapies to be controlled, tailored, and regulated by the patient's specific pharmacokinetic or pharmacodynamic attributes.

15. The method of claim **13** further comprising implanting a bridge into the jaw with multiple chambers where a polypharmacy regimen is required thus allowing a combination of therapies to be controlled, tailored, and regulated by the patient's specific pharmacokinetic or pharmacodynamic attributes.

16. The method of claim **13** where the apparatus is used as a form of automatic long term pharmacological therapy for a plurality of medicating agents and to improve patient compliance with a specified drug maintenance program.

17. The method of claim **13** further comprising dispensing medicating agents on demand via the use of selected timers or triggers.

18. The method of claim **13** further comprising sensing PKC concentration in the blood and timely releasing a medicating agent in proportion to the PKC concentration in the blood thus obtaining an effective mechanism for bipolar disorder.

19. The method of claim **13** further comprising evaluating different pharmacokinetic and pharmacodynamics behavior of a medicating agent including absorption, distribution, and elimination rates of the medicating agent, dose, cycle, and circadian time effects to improve effectiveness and efficiency.

**AN ARTIFICIAL TOOTH MEDICATING APPARATUS
FOR CONTROLLING, REGULATING, SENSING, AND RELEASING MEDICAL
AGENTS INTO THE BODY**

[0001] Background of the Invention

[0002] *Field of the Invention*

[0003] The invention relates to the field of administration of a medicating agent.

[0004] *Description of the Prior Art*

[0005] The existing art of dispensing medicating agents into the body is guided by the general formulas defining basic pharmacokinetic parameters such as absorption, distribution, and elimination from the body of the drug or agent. These parameters influence the maximum (peak) concentration and the area under the concentration-time-curve after a single oral dose.

[0006] Parameters such as the absorption rate constant which expresses the speed of absorption and the amount of fluid required to place the drug at a given concentration in the blood or plasma, are used to estimate the dose taking into account the elimination rate and clearance of the drug via renal, metabolic, and the biological half life of the medicating agents. These parameters are also used in calculating the dose given to the patient in conjunction with other outside factors such as the patient's clinical state, severity of the disorder, presence of a concurrent disease, and the use of other drugs.

[0007] The parametric definition of drug intake has been based on a statistical model which assumes the normal Gaussian distribution. This scenario is tailored to the patient's needs and the intake of medicating agents is an approximation that assumes an error limited only by the toxicity of the agent and its narrow margin of safety.

[0008] What is needed is an improvement in the art of medication dispensation for cases with a history of long term illness such as affective bipolar disorder, illnesses with symptoms including a spectrum of manic states, pain such as migraines, and in general neurological as well as psychiatric disorders.

[0009] Brief Summary of the Invention

[0010] The present invention describes a method by which specific adjustments and modifications are introduced to alter the multiple parametric mechanisms of drug intake based on patient-specific conditions. The invention provides the mechanism of sensory feedback to create a closed-loop approach in which the medicating agent and the body's metabolites are a part, thereby improving the art of medication and providing a patient-specific historical life-chart. This approach minimizes the error associated with the statistical Gaussian distribution associated with other prior art methods. The use of the invention will dramatically improve the course of treating chronic illnesses and improve patient compliance with a drug regimen.

[0011] The following invention deals with the development of a drug dispensing method and apparatus embedded in a prosthetic tooth, or dental

appliance, specifically, but not limited to, in the space of an extracted wisdom tooth. The entire system is preferably embedded inside an artificial tooth, and the tooth is implanted in the jaw-bone of a patient. The system is miniaturized and relies on the ability of a mechanical movement-kinetic mainspring winder or self-winding mechanism to supply the required energy needed to drive a plunger which dispenses the medicating agent via a perforated delivery duct. The self-winding mechanism in turn is driven by the normal movements of the jaw. The medication is replenished when necessary by a clinician or a physician using a refill dispenser.

[0012] The present invention is directed to an implanted apparatus to dispense medicating agents in a regulated and controlled manner. It is therefore an object of this invention to provide a system for dispensing medicating agents while controlling, regulating, sensing, and providing an "on-demand" option for the release of medicating agents to the patient's body by employing a tooth medicating apparatus within a cavity of an artificial tooth implanted in the mouth of a patient. The invention is effective, easy to use, and implantable preferably in the location of either the molar teeth (multicuspidate or grinders) or wisdom teeth (dentes sapientive). However, it is to be understood that the invention can also be employed in any position in the body where kinetic motion is available to power the pumping action of the dispenser.

[0013] Once implanted, the illustrated embodiment emulates the pharmacokinetic parameters of the medicating agent's dispensation through the use of the apparatus, namely the measurement of the absorption, distribution,

and elimination rates of the agent by employing a watch-like mechanism forming the kinetic mainspring winder which drives a plunger in a controlled fashion which dispenses the medicating agent. The watch-like mechanism uses the escapement mechanism to provide a constant real time delivery of medicating doses when activated. The use of timers in connection with the measured delivery rate also provides for an involuntary method of enhancing compliance (that is, to which degree a patient follows a treatment regimen) in intake of medicating agents under a strict, uniform, and controlled situation.

[0014] Specifically the watch-like mechanism assists in the dispensing of medicating agents by employing a mechanical movement and a kinetic mainspring winder so as to continuously regenerate energy to drive the plunger (pump mechanism) by the use of the kinetic winder converted from jaw movements. This mechanism then timely releases the medicating agents as specified by this embodiment of the invention to regulate the rate of change of the escapement and its subsequent assembly to define the rate of release of the medicating agent via the perforated delivery duct.

[0015] A tourbillon mechanism is employed to precisely regulate the escapement mechanism and to accurately release the energy generated by the drive wheel to activate the movement of the plunger which releases the medicating agent to a self-regulating pump which delivers the agent to the body.

[0016] The mechanism of the present invention also includes a mainspring barrel escapement assembly, balance assembly, hairspring, and a wheel and pinion assembly. Together these pieces when used in conjunction with the

tourbillon and the mechanical movement of the kinetic mainspring winder form an effective system to deliver the medicating agent at a specific rate of release.

[0017] A unidirectional valve using a refill dispenser is also present so as to replenish the medicating agent in the reservoir of the tooth medicating apparatus (TMD).

[0018] In summary, the illustrated embodiment is an implantable apparatus capable of delivering medicating agents to the body comprising a kinetic mainspring winder, a mechanical movement coupled to and driven by the kinetic mainspring winder; and a pump mechanism coupled to and driven by the mechanical movement, the pump mechanism delivering the medicating agents to the body at a time-measured rate.

[0019] The kinetic mainspring winder is an implant in a jaw bone.

[0020] The energy supplied to the kinetic mainspring winder is obtained from movement of the jaw bone.

[0021] The pump mechanism comprises a refillable reservoir for holding a medicating agent.

[0022] The pump mechanism further comprises an implant screw with a perforated delivery duct coupled to the apparatus for dispensing medicating agents into or near the adjacent blood vessels in the jaw bone.

[0023] The apparatus comprises a jaw implant, the jaw having a jaw plane and further comprising a means for positioning the rotor of the kinetic mainspring winder at a 5 degree inclination relative to the jaw plane.

[0024] The apparatus further comprises a timer and clutch mechanism coupled between the mechanical movement and the pump mechanism for selective dispensing the medicating agent into the body.

[0025] In another embodiment the invention includes an implantable apparatus capable of delivering at least one medicating agent to the body comprising a Faraday generator powered by jaw movements, a electrical power circuit coupled to the Faraday generator for storing electric energy generated by the Faraday generator, an electrically powered pump coupled to the electrical power circuit for delivering the medicating agents to the body, at least one sensor for providing a feedback signal related to the medicating agent, and a regulator coupled to the electrical power circuit and coupled to and controlling the pump, the regulator coupled to the sensor and controlling the pump based on the feedback signal.

[0026] The regulator comprises a multiplexer, a signal amplifier having an input coupled to the multiplexer, an analog-to-digital converter having an input coupled to the signal amplifier, a microcontroller having an input coupled to the analog-to-digital converter, and a plurality of sensor elements coupled to the multiplexer including at least one of: a free ion detector; a pulse rate sensor; a blood chemistry analyzer; and/or a body temperature sensor.

[0027] The regulator further comprises a ROM, RAM, or NVM microchip or any combination thereof coupled to the microcontroller for the purposes of data storage.

[0028] The illustrated embodiment of the invention is also a method for dispensing medicating agents into a body of a patient using an implant in a jaw bone of the patient comprising the steps of storing at least one medicating agent in the implant; storing energy from normal jaw movements; selectively converting the stored energy into controlled pumping of the at least one medicating agent stored in the implant in the jaw bone, to selectively dispense the medicating agent stored in the implant into a blood flow path in the jaw bone at a controlled rate.

[0029] The method further comprises the step of sensing at least one sensed biological input or user controlled input, and selectively controlling dispensing a medicating agent stored in the implant into the blood flow path in the jaw bone by at least one sensed biological input or user controlled input.

[0030] The method further comprises the step of providing a plurality of implants in the jaw bone for a polypharmacy treatment thus allowing a combination of therapies to be controlled, tailored, and regulated by the patient's specific pharmacokinetic or pharmacodynamic attributes.

[0031] The method further comprises the step of implanting a bridge into the jaw with multiple chambers where a polypharmacy regimen is required thus allowing a combination of therapies to be controlled, tailored, and regulated by the patient's specific pharmacokinetic or pharmacodynamic attributes.

[0032] The method includes the embodiment where the apparatus is used as a form of automatic long term pharmacological therapy for a plurality of

medicating agents and to improve patient compliance with a specified drug maintenance program.

[0033] The method further comprises the step of dispensing medicating agents on demand via the use of selected timers or triggers.

[0034] The method further comprises the step of sensing PKC concentration in the blood and timely releasing a medicating agent in proportion to the PKC concentration in the blood thus obtaining an effective mechanism for bipolar disorder.

[0035] The method further comprises the step of evaluating different pharmacokinetic and pharmacodynamics behavior of a medicating agent including absorption, distribution, and elimination rates of the medicating agent, dose, cycle, and circadian time effects to improve effectiveness and efficiency.

[0036] While the apparatus and method has or will be described for the sake of grammatical fluidity with functional explanations, it is to be expressly understood that the claims, unless expressly formulated under **35 USC 112**, are not to be construed as necessarily limited in any way by the construction of "means" or "steps" limitations, but are to be accorded the full scope of the meaning and equivalents of the definition provided by the claims under the judicial doctrine of equivalents, and in the case where the claims are expressly formulated under **35 USC 112** are to be accorded full statutory equivalents under **35 USC 112**. The invention can be better visualized by turning now to the following drawings wherein like elements are referenced by like numerals.

[0037] Brief Description of the Drawings

[0038] Fig. 1 is a side cross-sectional view of a mechanical embodiment of the tooth medicating apparatus (TMD) depicting the main assemblies forming the dispenser, pump mechanism and the kinetic winder.

[0039] Fig. 1a is an exploded perspective view of the TMD as it depicts the main mechanical components of the apparatus and its spatial layout.

[0040] Fig. 2 is a side cross-sectional view depicting the tooth medicating apparatus with the refill dispenser and a graphic illustration of blood vessels adjacent to the perforated delivery duct.

[0041] Fig. 2a is a side cross-sectional view of the refill dispenser.

[0042] Fig. 2b is a side cross sectional view of the invention with two chambers used in an orthodontic bridge implant configuration.

[0043] Fig. 3 is a top plan interior view of the crown containing the tourbillon and the kinetic mainspring winder.

[0044] Fig. 3a is an exploded perspective view of the kinetic winder and the mainspring barrel connected to the escapement mechanism and the drive wheel.

[0045] Fig. 3b is a diagram depicting the kinetic winder alignment, relative to axis of gravitation.

[0046] Fig. 4 illustrates a top plan interior view of the crown and the relation between the drive wheel and the barrel pinion, driver pipe and the plunger.

[0047] Fig. 4a is a side interior plan view of the pump assembly of the

dispenser and the worm gear mechanism.

[0048] Fig. 4b is a side interior plan view of the pump assembly of the dispenser and the worm gear mechanism and adjustable timer modified with a clutch assembly for control of time release schedule.

[0049] Fig. 5 is a top interior view of the crown and is an orthographic view of the mainspring barrel, barrel wheel, barrel harbor and the ratchet wheel.

[0050] Fig. 6 is a top interior plan view of the crown which graphically represents the escapement mechanism which houses the tourbillon regulating energy- delivery to the plunger.

[0051] Fig. 7 is a diagrammatic representation of the escape wheel, the pallet fork, the pallet cock and the escape pinion which advances the tourbillon cage.

[0052] Fig. 8 is an plan view of the layout of a printed circuit board (PCB) module assembly containing the sensor and microcontroller used in another embodiment of the TMD which is an optional architecture incorporating sensor (s) and electronic assembly..

[0053] Fig. 8a is a top plan view of the Faraday pendulum generator and a modified asymmetric weighted rotor in the embodiment using the PCB of Fig. 8.

[0054] Fig. 8b is an exploded perspective view of the medicating agent dispensing apparatus of Figs. 8 and 8a, showing the three major parts of the device; the Faraday generator, the electronics module, and the dispensing container.

[0055] Fig. 8c is a top diagrammatic view of the Faraday generator with its E-frame coil assembly and the associated integrated magnetic element of the asymmetric weight rotor.

[0056] Fig. 8d is in the left hand portion a block diagram of the embodiment of the TMD having multiple sensors and in the right hand portion a diagram of the physical components of the TMD. The sensors can vary and be of a general type such as for temperature measurement, or specific such as pulse rate sensor or a C_a^{++} free ions detector.

[0057] Fig. 8e is a schematic diagram of the TMD depicting the sensor and the servo closed loop architecture.

[0058] Fig. 8f is a schematic diagram of the Faraday generator with its pendulum topology, storage capacitor and a rectifier circuit.

[0059] Fig. 9 is a diagrammatic illustration of a molar tooth implant on the lower jawbone, both on the left and the right side of the jaw, as a possible location for implanting the artificial tooth medicating dispenser. Fig. 9 further depicts other possible implant positions for the artificial tooth including an orthodontic bridge for use in a polypharmacy medicating configuration.

[0060] The invention and its various embodiments can now be better understood by turning to the following detailed description of the preferred embodiments which are presented as illustrated examples of the invention defined in the claims. It is expressly understood that the invention as defined by the claims may be broader than the illustrated embodiments described below.

[0061] Detailed Description of the Preferred Embodiments

[0062] The illustrated embodiment of the invention is an apparatus and a method for using an artificial tooth assembly, generally denoted in Fig. 1 by reference numeral **1800**, to dispense medicating agents to the body. The apparatus **1800** is useful for controlling the amount and duration a particular medicating agent(s) is released into the body when treating any number of physical or psychological ailments.

[0063] Fig. 1 is an side cross sectional representation of the tooth medicating apparatus (TMD) **1800** comprising the primary a base section **100**, a jacket section **200**, and a crown section **300**. The crown section **300** houses the mainspring barrel assembly **400**, and the tourbillon balance assembly **600**. Fitted to the base **100** is one or more surgical implant screws **101** with a perforated delivery duct **102** and is connected to a refillable reservoir **201** shown in Fig. 2 inside the jacket **200**. The crown section **300** is fitted with a refill valve **301** which connects via the refill duct **302** to the reservoir **201** passing though the driver pipe **204** as seen in Fig. 2.

[0064] Fig. 1a is an isometric representation of the TMD apparatus **1800** depicting the functional and mechanical arrangement comprising a pump assembly **1500** with a worm-gear arrangement formed by the plunger **203** and driver pipe **204**. The energy for driving pump **1500** is obtained from kinetic winder **500** and comprises plunger **203** and driver pipe **204**. The movement of

worm-gear assembly **203** and **204** generates the pressure differential necessary to drive and deliver the medicating agents and/or fluids **202** via the perforated duct **102**.

[0065] Fig. **1a** further depicts the internal working mechanism of the embodiment. The crown mechanism assembly **300** is shown with its refill valve **301** connected to refill duct **302**. The invention further comprises a kinetic winder **500** which stores and converts the energy necessary for driving the TMD pump **1500** comprised of driver pipe **204** and plunger **203**. Items **203** and **204** form a worm-gear assembly **1501** in Fig. **4a** whose driving energy is obtained from the movement of the jaw bone **50** (shown in Fig. **9**) whose energy is transferred to the spring rotor or asymmetric weight **501** (shown in Fig. **3**) of the kinetic winder **500**. Fig. **1a** further depicts the energy from kinetic winder **500** is stored in the main spring barrel **400** which further regulates the energy transfer through the tourbillon assembly **600**. This energy transfer is further adjusted by the balance subassembly **700** which releases the necessary amount of energy required to move the plunger **203** onto the driver pipe **204** which results in the drive assembly **1501** in Fig. **4a** displacing and compressing the medicating agent and /or fluid **202** through the perforated duct **102**. Figs. **1** and **1a** depict that whenever energy is stored in spring barrel **400** the watch mechanism will operate resulting in a constant expression of drug through duct **102** into the bloodstream or tissue of the jaw.

[0066] The present invention is further understood in Fig. **1a** through the action movement of the drive wheel **205** and the fixed wheel **604** driving the

plunger **203** while compressing the chamber **201** so as to cause the medicating agent **202** to be displaced via the perforated duct **102** through the adjacent blood vessels **60** (in Fig. 2) located in the jaw-bone area such as a molar tooth cavity **70** in Fig. 9.

[0067] Fig. 2 shows the detail of the reservoir **201** containing medicating agents **202** which are expelled by a plunger **203** as it moves down the threaded driver pipe **204**. As the medicating agents are dispensed, they are absorbed into the nearby blood vessels **60** and carried to the brain and other portions of the body. When refilled, the new medicating agents enter the reservoir through the refill spigot **206** at the base of the threaded driver pipe **204**.

[0068] The refilling process of the reservoir **201** is depicted in Fig. 2a. The refill device **900** filled with medicating agent **202** and comprising a refill nozzle **901** and a plunger **902**. The plunger **902** forces the medicating agent **202** from the refill nozzle **901** through the refill duct **302** into the reservoir **201** as illustrated by Fig. 2.

[0069] Fig. 3 shows a top interior view of the crown **300** and the watch-like mechanism that powers the device including the arrangement of the tourbillon balance assembly **600** with the mainspring barrel **400**. The mainspring **403**, which is illustrated in Fig. 5, is loaded by the movement of an asymmetrically weighted rotor **501** and mounted to a bearing and wheel **502** and fixed to a ratchet **503** which is caught by a ratchet cock **504** and held by the ratchet spring **505** which is mounted on the ratchet cock **505**.

[0070] Fig. 3a is an isometric view of the kinetic winder **500** (Fig. 1a) with

its asymmetric rotor **501**, ratchet wheel **502**, ratchet **503**, ratchet cock **504**, and ratchet spring **505**. The mechanical energy of movement of the jaw bone **50**, depicted in Fig. **9**, is transferred to the asymmetric rotor **501** due to its dynamic imbalance. Explicitly, the asymmetric rotor **501** transfers energy by engaging the ratchet wheel **502** thereby causing it to move in a unidirectional manner. The ratchet **503**, ratchet cock **504**, and ratchet spring **505** prevent the cancellation of the action as the asymmetric rotor **501** rotates in the opposite direction.

[0071] The use of the kinetic winder **500** in the context of this invention is to provide a continuous generation of energy that is stored in the mainspring barrel **400** by capturing any mechanical energy generated through various movements of the jaw bone **50** due to the asymmetric weight of the rotor **501** relative to the axis of gravity. Fig. **3b** depicts the alignment of the asymmetric rotor **501** relative to the TMD implant, which is positioned at a **5** degree inclination from the horizontal jaw plane. Tilting the plane of the rotor **501** with respect to the axis of gravity **40** allows greater generation of energy needed to power the invention by improving the propensity of the rotor **1900** to pick up jawbone **50** movements.

[0072] Fig. **3a** further depicts the action potential of the rotor **501** relative to the mainspring barrel **400** mentioned in Fig. **1a** containing the barrel pinion **401**, barrel wheel **402**, mainspring **403**, barrel arbor **404**, and arbor bearing **405**. The mainspring barrel **400** drives the mainspring **403** while the barrel arbor **404** rotates with the ratchet wheel **503**. Fig. **3a** further shows the movement of the barrel **402** which rotates the barrel pinion **401**. The barrel pinion **401** meshes

with drive wheel **205** thereby engaging barrel pinion **401** in order to rotate the driver pipe **204** while advancing the plunger **203** through the reservoir **201** as previously shown in Fig. **1a**.

[0073] Fig. **4** shows the drive wheel **205** which is engaged by the barrel pinion **401** which moves with the barrel wheel **402** (not shown) in order to rotate the driver pipe **204** and advance the plunger **203** through the reservoir **201** as previously shown in Fig. **1a**.

[0074] Fig. **4a** shows a side view of the reservoir **201**, the plunger **203**, the driver pipe **204**, and the drive wheel **205** which form pump **1500**. Pump **1500** creates the action of the worm gear **101** expelling the medicating agent **202** when driven by the barrel pinion **401**. The worm gear movement as described by Fig. **4a** can be further modified to include a suitable coil and rectified electrical circuit which would thereby generate the energy necessary to power the CMOS based assembly noted by element **30** as shown in Figs. **8**, **8a**, **8b**, **8d**, and **8e**.

[0075] Fig. **5** depicts the mainspring barrel **400** comprising a barrel wheel **402** driven by the mainspring barrel **403**. The mainspring barrel **403** is fixed at the center to the barrel arbor **404** which rotates with ratchet wheel **503** in Fig. **3a** to load the spring.

[0076] Fig. **6** shows that the advancement of the mainspring barrel **400** is regulated by an escapement **700** and housed within a tourbillon cage **603** which rotates around a fixed wheel **604**. Fig. **5** further shows that on cage **603**, a pinion (not shown) engages the barrel wheel **402** via a bridge movement **601**. Fig. **6** further depicts balance wheel **701** oscillating by way of a hairspring **702** which is

fixed to an adjustable mobile tensing stud **703** causing regular intervals of energy to release from the mainspring **403**.

[0077] Fig. **7** shows that the escape wheel **605** depicted in Fig. **6** and pallet fork **803** are mounted to pivots on the pallet cock **801**. The roller jewel pin **807** moves with the balance wheel **701** shown in Fig. **6** and kicks the pallet fork **803** between two banking pins **806** which alternately releases and catches the escape wheel **605** with the pallet stones **805** which are held by pallet fork **803**. The escape wheel **605** turns the escape pinion **802**, which engages the fixed wheel **604** and advances the tourbillon cage **603**, the barrel wheel **402**, the drive wheel **205**, and the plunger **203** expelling the medicating agent **202** as shown in Figs. **4a**, **5**, and **6**.

[0078] Finally, Fig. **9** illustrates the implanting of the TMD in the space of a molar tooth or alternatively in the location of a previously removed wisdom tooth. The entire assembly disclosed above is contained within the artificial tooth which comprises a base **100**, a jacket **200**, a crown, **300** and an implant post **102** made of titanium as depicted in Fig. **1**. The metal anchor **102** acts as a substitute for wisdom tooth implant **74**. The device is surgically implanted into the jawbone **50**. The bone bonds with the titanium post **102** thereby creating a strong foundation for an artificial tooth within the blood vessel **60** surrounding the jaw-bone **50** as illustrated by Fig. **2**. Small posts are then attached to the implant which protrudes through the gums. These posts provide stable anchors. The above disclosed device is customarily implanted by an orthodontic surgeon.

[0079] Many patients fail to respond to treatment due to the lack of efficacy or the production of side-effects which leads to patient non-compliance with the medicating regimen. The invention as disclosed above can be used to improve the art of dispensing medicating agents for many cases. For example, patients who suffer from acute manic episodes may use the present apparatus as a form of pharmacological therapy and use any number of typical anti-psychotic drugs as a maintenance program including lithium, valproate, and carbomaezine.

[0080] Another use of the apparatus is to specifically improve the treatment of bipolar affective disorders because as clinical evidence suggests, medicating agents such as lamotrigine (LTG) have shown a broad spectrum of utility by inhibiting neural hyper excitability and modifying synaptic plasticity via usage of a voltage (-) dependent inhibitor of neuronal voltage activated Na^+ channels and possibly Ca^{++} . For example, Protein Kinase C (PKC) concentrations play a significant role in the pathophysiology of bipolar disorders. The effect of lithium and its concentration tend to attenuate the PKC function and thus the use of the pump and its associated watch-like mechanism of the claimed invention improve the ability to regulate and medicate the patient in such processes. Clinical observations indicate that the signal transduction mechanisms in bipolar disorders are associated with intercellular calcium homeostasis. The claimed invention can release the medicating agent in correct proportion to the PKC concentration and the watch-like mechanism of the claimed invention enables one to accurately and timely release the medicating agents thereby obtaining a effective mechanism for such treatments.

[0081] The current invention will also enable drug manufacturers to evaluate the effectiveness of its drugs during animal and clinical studies because of details provided from the local delivery from the tooth medicating apparatus, specifically the absorption, distribution, and elimination of a tested drug in a local setting. Other characteristics such as dose, cycle, circadian time effects, and the entire pharmacokinetic as well as pharmacodynamic behavior of the medicating agents can be evaluated employing the TMD apparatus because of its local delivery and ability to provide controlled dispensation associated with its watch-like mechanism.

[0082] In another embodiment of the invention, the apparatus is used in a poly-pharmacy regimen when more than one medicating agent is required. Fig. 2b illustrates an orthodontic bridge **73** which incorporates two containers **201** so as to afford a poly-pharmacy approach. The reservoir **201** containing medicating agents **202** which are expelled by a plunger **203** as it moves down the threaded driver pipe **204**. As the medicating agents are dispensed, they are absorbed into the nearby blood vessels **60** and carried to the brain and other portions of the body. When refilled, the new medicating agents enter the reservoir through the refill spigot **206** at the base of the threaded driver pipe **204** as previously disclose above.

[0083] Fig. 9 also further illustrates a TMD implant in the location of molar tooth cavities **70**, **71** and **72** in the side of the jaw. The apparatus is shown in Fig. 9 at tooth number **32** (3rd molar). Similarly, Fig. 9 depicts a possible arrangement of a comprehensive bridge **73** implanted at the lower teeth of

jawbone **50**. The apparatus is an integral part of the bridge while reservoir **201** (shown in Fig. **2**) is expanded to include larger or multiple chambers for use in cases where a polypharmacy regimen is required.

[0084] This particular embodiment of the invention the apparatus provides a controlled mechanism for cases where polypharmacy is essential in treating patient-resistant euphoric mania (characterized by elevated mood, hyperactivity, rapid speech, refractory to standard treatments and anticonvulsants). The use of a polypharmacy approach shows dramatic improvements in symptoms and with the aid of the apparatus, the regulating of multiple medicating agents (polypharmacy) will be more obvious and intuitive. For example, when dealing with a bipolar illness, treatment by single agents is not always effective. Supplemental anti-depressants, anti-manic, antipsychotic, or hypnotic medicating agents must sometimes be used. However, these traditional adjunctive medications are associated with potential problems such as mania, accelerated neuroleptics, dyskinesia, etc. The use of the apparatus and the method presented allows a combination of therapies to be controlled, tailored, and regulated by the patient's specific pharmacokinetic and pharmacodynamic attributes.

[0085] In yet another embodiment of the invention, the apparatus is configured to provide the user with an "on demand" option for dispensing the medicating agents. Fig. **4b** is a side interior plan view of reservoir **201** depicting an alternate drive configuration which comprises a user-adjustable mechanical timer and clutch assembly **350**. The adjustable mechanical timer and clutch

assembly **350** is analogous to the principle behind an alarm clock timer, which is clear to those familiar in the art, and is capable of adjusting the amount of medicating agent **202** to be dispensed based on prescribed mechanical settings. The adjustable timer and clutch assembly **350** diverts the transfer of energy from the barrel wheel **402** to the barrel pinion **401** and then to a mechanical timer (not shown) which triggers the clutch to engage the barrel pinion **401** only for the duration of the timed release. The mechanical timer and clutch assembly **350** may be mechanically controlled by conventional adjustments (not shown) manipulated by the physician or may be electronically controlled through conventional software control of conventional electromechanical timers.

[0086] This particular embodiment of the invention allows dispensation of the medicating agents with the use of an "on demand" feature via the use of "timers" or "triggers". This is especially helpful when used to correct and provide effective implementation of medicating agents for conditions such as erectile dysfunctions due to the ability of the apparatus to provide an on-demand option for the release of medicating agents to the patient's body. For example, in order for medicating agents such as Viagra to correct erectile dysfunction (ED), they need to inhibit phosphodiesterase Type **5** (PDE**5**) which is a specific marker and requires a timed release based on user decision, specifically to erect the target penis. However use of the claimed invention can better achieve this result and make it more intuitive and obvious because the patient can select any specific time to dispense the medicating agent.

[0087] In yet another embodiment of the invention, the apparatus contains a device known as an electronic regulator **30** as illustrated in Fig. **8**. This device enables one to sense, control, regulate, and dispense medicating agents into a patient's jaw bone **50** shown in Fig. **9**. The electronic regulator **30** further contains a free ion sensor **9** which detects minute changes (elevation) in Ca^{++} concentration. The output of the free ion sensor **9** is coupled to the input of an instrumentation amplifier **8** and amplifies the signal from the free ion detector **9** as shown in the schematic of Fig. **8d**. The amplification rate is a function of resistor value. The output signal from the amplifier **8** is fed to the input of an analog to digital converter (ADC) **7**. After determining the value of free ion concentration from the use of a lookup table residing in a ROM (read only memory), RAM (random access memory), or NVM (nonvolatile memory) microchip **45** coupled to ADC **7**, it is transmitted via the ADC **7** to a microcontroller **1**. The pump **1500** with its worm gear **1501** is activated (as shown in Fig. **4a** and/or optional configuration as noted by Fig. **4b**) to deliver the medicating agent **202** via the perforated duct **102** as further described by Fig. **8b**.

[0088] Figures **8** and **8a** also depict the relative location of the electronic assembly forming the regulator which controls the dispensation of the medicating agent from the apparatus. Fig. **8** further depicts the necessary building blocks to configure the electronic regulator **30** with a plurality of sensor elements such as a free ion detector **9**, a pulse rate sensor **48**, blood chemistry analyzer **49**, body temperature sensor **46**, a multiplexer **44**, a microcontroller **1**, an op amp **8**, a DAC **2**, and a ADC **7**, a capacitor **1905**, a rectifier circuit **1906**, and an electric

motor **95**. The above noted building blocks that form electronic regulator assembly **30** can be easily ascertained by those who are familiar with the art.

[0089] Figures **8d** and **8e** are block diagrams which illustrate the general outline of the electronic regulator. The block diagram of Fig. **8e** illustrates the relationship between the sensing leg (e.g. elements **9**, **46**, **48**, and **49**) and the microcontroller **1** to enable the TMD apparatus to regulate the dispensation of the medicating agent **202** while employing a worm gear **1501** and the pump action **1500** as described above.

[0090] Figures **8d** and **8e** further detail the preferred embodiment shown by Figs. **8**, **8a**, **8b**, **8c**, **8d**, and **8e** whereby an array of sensors, such the pulse sensor **48**, temperature sensor **46**, free ion sensor **9**, and a blood chemistry analyzer **49** are incorporate multiplexer **44**, which allows the microcontroller **1** to sample the various sensors at a sampling rate defined by the program residing in the microcontroller **1**. The multiplexer used in this case is the Motorola PIC12LC672 and its function is well known in the art.

[0091] Finally, the schematic depicted in Fig. **8e** illustrates that the sensors such as the pulse sensor **48** are coupled to the multiplexer **44**. The pulse sensor **48** is a miniature electronic condenser microphone that sends a signal to the input of the multiplexer **44**. The multiplexer **44** then sends the signal out to the amplifier **8** which amplifies the signal and feeds it to the A-to- D converter **7** which is a part of the microcontroller **1**. Microcontroller **1**, part number PIC12LC672, has an A-to-D converter **7** and either a ROM, RAM, or NVM microchip **45** or combination thereof built in. Once the signal from the pulse rate

sensor **48** senses the pulse rate from within the jaw **50**, it is sent to the microcontroller **1** which analyzes the data and stores them for retrieval. Due to the pulse rate background noise, a Fast Fourier Transform (FFT) can be used as part of ROM **45**. The electrical power to operate all the electronics is obtained from the kinetic winder **1900**.

[0092] In yet another embodiment of the invention, the apparatus uses the energy from the mechanical movement of the jaw bone to power a Faraday generator which in turn then provides electric power to the device. It is to be expressly understood that the following explanation of the physical principles involved in the invention are not to be limiting in any way on the claims. All of the scientific explanations and descriptions presented below are meant to be illustrative only and are provided in order to help better understand the invention and what is being claimed as a whole.

[0093] A simplified description of the minimal geometry required in generating the necessary EMF used in the invention is noted by the Faraday-Maxwell Induction Rule:

$$\mathcal{E} = -N \frac{d\Phi_B}{dt} ,$$

[0094]

[0095] where \mathcal{E} is the electromotive force (emf) in volts, N is the number of turns of wire, and Φ_B is the magnetic flux in webers through a single loop. More generally, the relation between the rate of change of the magnetic flux through a surface S enclosed by a contour C (see Fig. **8c** for spatial layout of the "contour C " which can be numerically parameterized by calculating the coil **1902**

size relative to the frequency of rotation of the asymmetric weight rotor **1900** with its integrated set of magnets **1901**). Rendering the invention its metric value so as to generate the necessary energy to power the electronic module **30**, we further calculate the electric field along the "contour C" by the use of Faraday's law of induction as:

[0096]
$$\oint_C \mathbf{E} \cdot d\mathbf{l} = - \frac{d}{dt} \int_S \mathbf{B} \cdot d\mathbf{A}$$

[0097] In this equation \mathbf{E} is the electrical field, $d\mathbf{l}$ is an infinitesimal element of the contour C, and \mathbf{B} is the magnetic field.

[0098] The schematic in Fig. 8f depicts the use of a modified Faraday generator using a pendulum mechanism **1900**. The Faraday principle is employed to create rapid flux changes across a coil **1902**. The optimal topology for this principle is the use of a pendulum mechanism which swings on its axis of rotation **40** due to the jaw bone movement **50**. Alternating polarity NdFeB magnets **1901** on the edge of the pendulum enable a rapidly changing magnetic flux. By employing the Faraday induction principle we can calculate and predict the effect of the pendulum **1900** oscillation with reference to the coil **1902** size and the ferrite core **1903**.

[0099] The volume and space allotted for the TMD apparatus requires a reduction in size of a super capacitor C1 **1904.8** such as a Sieko XH-HG ultra capacitor as depicted in Fig. 8f. It is important to provide a good source of averaged pulsed power and this task is achieved by using a three phase coil assembly **1902** mounted on the E frame **1903**. The coils **1902** are wound onto

an E shaped curved ferrite core **1903**. The pendulum **1900** swings the magnets across the pole faces of the E core and thus alternates the flux through them. The coils are inductively induced with voltage. The rising voltages across the coils are then converted into direct current by a DC rectifier and energy storage system **1904**. The three phase diode bridge rectifier is comprised of six diodes: D1 **1904.1**, D2 **1904.2**, D3 **1904.3**, D4 **1904.4**, D5 **1904.5**, and D6 **1904.6**. The rectifier diodes are clamped by a low leakage zener diode Z1 **1904.7** which clamps the voltage to 3V. The voltage appearing across Z1 **1904.7** is also seen across C1 **1904.8**. The capacitor is charged by the rectified current of the bridge rectifier **1904**. The power supply shown in Fig. 8f can provide a steady source of voltage to the CMOS microprocessor **1** mounted on circuits **30**.

[00100] Fig. 8a depicts the Faraday pendulum assembly **1900**, the rotor **1901**, and inserted magnets **1902** aligned with coil **1903** and wrapped on the frame **1904**. Fig. 8b is an exploded perspective view of the connection of Faraday assembly **1900** to the capacitor **1905** (Fig. 8) on the PCB **30**, and the electric motor **95** which drives the barrel pinion **401**. The above noted architecture provides for the incorporation of a servo closed loop modality **53** (see Fig. 8e) so as to enable the TMD apparatus **1800**, to modify its medicating agent(s) **202** rate of dispensation and further regulating the rate of absorption, distribution, and elimination relative to the multiple parametric mechanisms of drug intake based on patient-specific conditions as previously defined by the microcontroller **1** and the look-up tables residing in the RAM, ROM, or NVM microchip **45**.

[00101] Techniques of employing magnets in order to control and stabilize the pendulum are described in U.S Patents **4,723,233** to Beebe, **3,885,753** to Connor, **3,100,278** to Reich, and **7,306,364** to Born et al. are incorporated herein by reference. The above mentioned patents teach that the use of a pendulum in conjunction with permanent magnets or electromagnets for the purpose of adjusting and stabilizing the pendulum to keep an accurate time. All the above patents disclose a mechanism by which the pendulum is controlled by fixed magnets so that the pendulum oscillations and unexpected deviations in space and or in time are corrected by a magnetic force. The use of a Faraday pendulum generator in this embodiment is related to the ability of the asymmetric rotor **1900** to harness the kinetic energy generated by a jawbone movement **50**, to “translate” the energy of the natural displacement of the jawbone **50** to drive the movements of the asymmetric rotor **1900**, and thence to generate electrical power from the relative motion of the magnets and the coils in the Faraday generator.

[00102] The above action is used to generate the necessary energy to power the command and control circuitry of motor **95** in Fig. **8b** to dispense the medicating agents **202**. The resultant EMF generated from the Faraday pendulum **1900** (and its associated circuit **1904** and capacitor **1904.8** in Fig. **8f**) thereby enables the transfer of energy to an electric motor **95** that drives the barrel pinion **401** and the plunger **203** by the use of a worm gear mechanism **1501** to create a pumping action. The resulting displacement of the medicating agent **202** is further controlled by a servo closed loop **53** schema noted in Fig. **8e**

which regulates (by modifying or amplifying) the delivery of the medicating agent **202**. This action is regulated by the by the conventional use of microcontroller **1** and look-up tables residing in the memory modules **45** while being governed by the closed servo loop modality **53** described in Fig. **8e**. The electrical power to operate all the electronics is obtained from the kinetic winder **1900** driving the Faraday generator and stored in a capacitor.

[00103] In the final embodiment that the applicant contemplates, the apparatus uses the kinetic winder **500** to power both the electronic circuit **30** as depicted in Figs. **8a** and **8b** and disclosed above and the pump **1500** as depicted in Fig. **1a**. This embodiment is different from the previous contemplated embodiments in that the energy needed to operate the pump **1500** and the energy needed to drive the electronic circuit **30** come from the same source. The kinetic winder **500** obtains energy form the mechanical movement of the jawbone **50** as disclosed above and depicted in Fig. **9**. The energy that is supplied to electronic circuit **30** by the kinetic winder **500** drives the circuit and its various sensor elements as disclosed above. When the circuit **30** has determined that medication is needed in the patient's body, a signal is sent to the pump **1500**. The pump **1500** then begins to dispense the medicating agent out of the apparatus as disclosed above using energy obtained by the kinetic winder **500**. In other words, the present embodiment envisions that the kinetic winder **500** powers all of the various elements of the claimed apparatus and is coupled to those elements in order to distribute the energy obtained from the movement of jawbone **50**.

[00104] Many alterations and modifications may be made by those having ordinary skill in the art without departing from the spirit and scope of the invention. Therefore, it must be understood that the illustrated embodiment has been set forth only for the purposes of example and that it should not be taken as limiting the invention as defined by the following invention and its various embodiments.

[00105] Therefore, it must be understood that the illustrated embodiment has been set forth only for the purposes of example and that it should not be taken as limiting the invention as defined by the following claims. For example, notwithstanding the fact that the elements of a claim are set forth below in a certain combination, it must be expressly understood that the invention includes other combinations of fewer, more or different elements, which are disclosed in above even when not initially claimed in such combinations. A teaching that two elements are combined in a claimed combination is further to be understood as also allowing for a claimed combination in which the two elements are not combined with each other, but may be used alone or combined in other combinations. The excision of any disclosed element of the invention is explicitly contemplated as within the scope of the invention.

[00106] The words used in this specification to describe the invention and its various embodiments are to be understood not only in the sense of their commonly defined meanings, but to include by special definition in this specification structure, material or acts beyond the scope of the commonly defined meanings. Thus if an element can be understood in the context of this

specification as including more than one meaning, then its use in a claim must be understood as being generic to all possible meanings supported by the specification and by the word itself.

[00107] The definitions of the words or elements of the following claims are, therefore, defined in this specification to include not only the combination of elements which are literally set forth, but all equivalent structure, material or acts for performing substantially the same function in substantially the same way to obtain substantially the same result. In this sense it is therefore contemplated that an equivalent substitution of two or more elements may be made for any one of the elements in the claims below or that a single element may be substituted for two or more elements in a claim. Although elements may be described above as acting in certain combinations and even initially claimed as such, it is to be expressly understood that one or more elements from a claimed combination can in some cases be excised from the combination and that the claimed combination may be directed to a subcombination or variation of a subcombination.

[00108] Insubstantial changes from the claimed subject matter as viewed by a person with ordinary skill in the art, now known or later devised, are expressly contemplated as being equivalently within the scope of the claims. Therefore, obvious substitutions now or later known to one with ordinary skill in the art are defined to be within the scope of the defined elements.

[00109] The claims are thus to be understood to include what is specifically illustrated and described above, what is conceptionally equivalent, what can be

obviously substituted and also what essentially incorporates the essential idea of the invention.

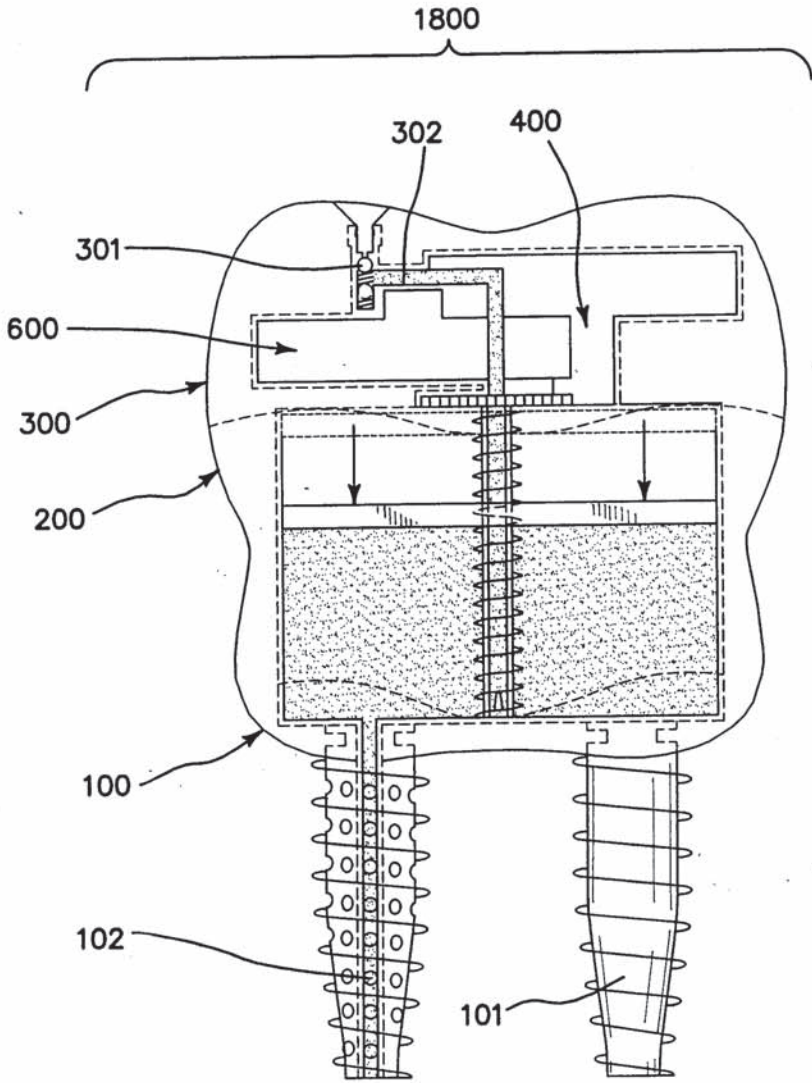


FIG. 1

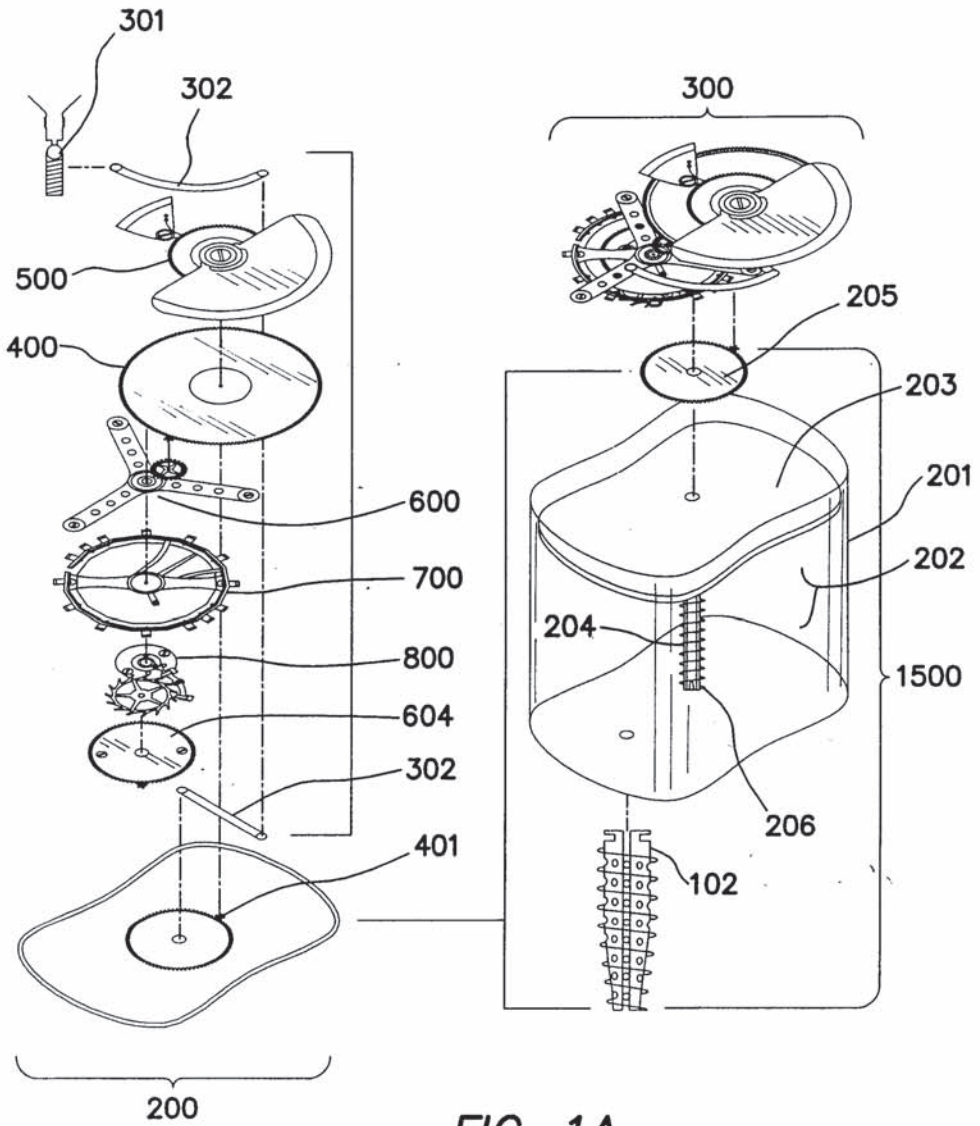


FIG. 1A

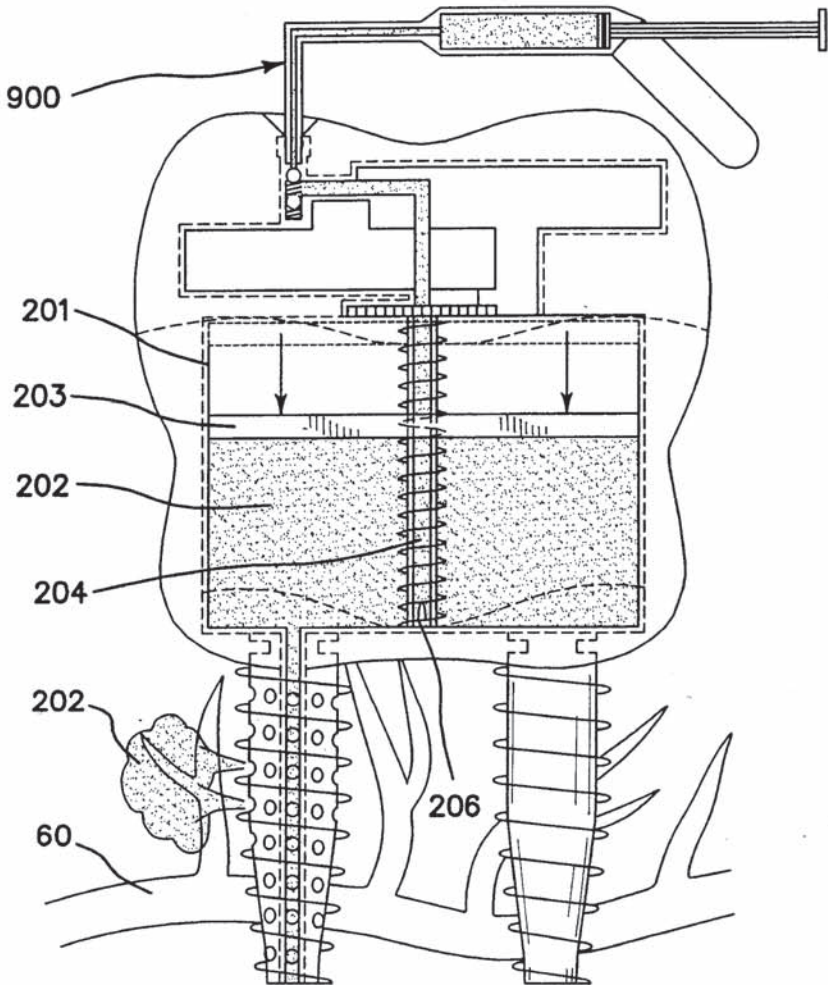


FIG. 2

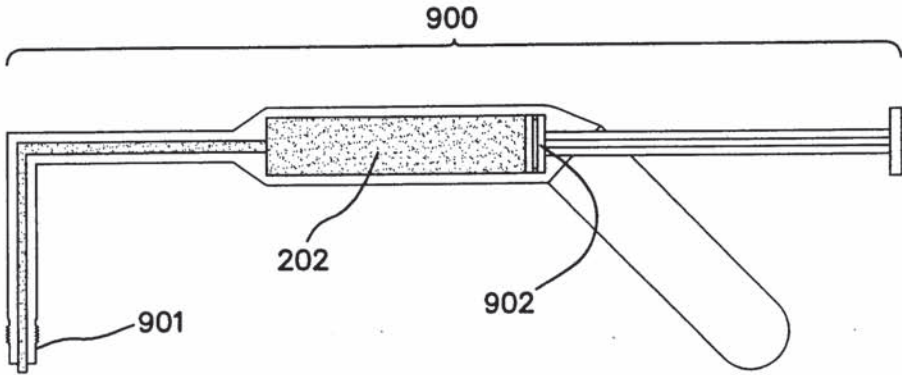


FIG. 2A

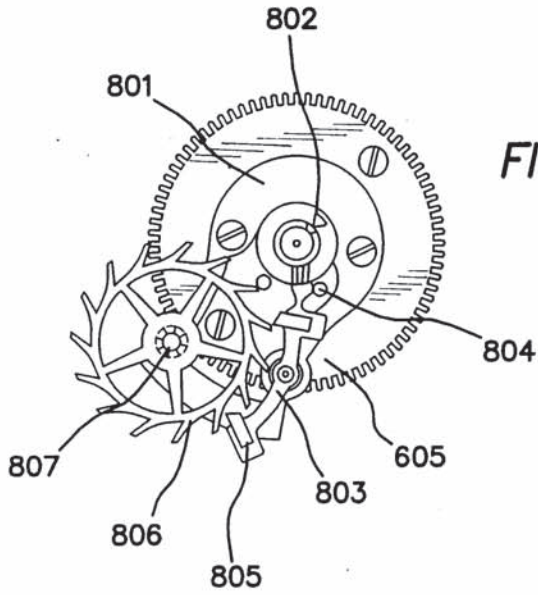
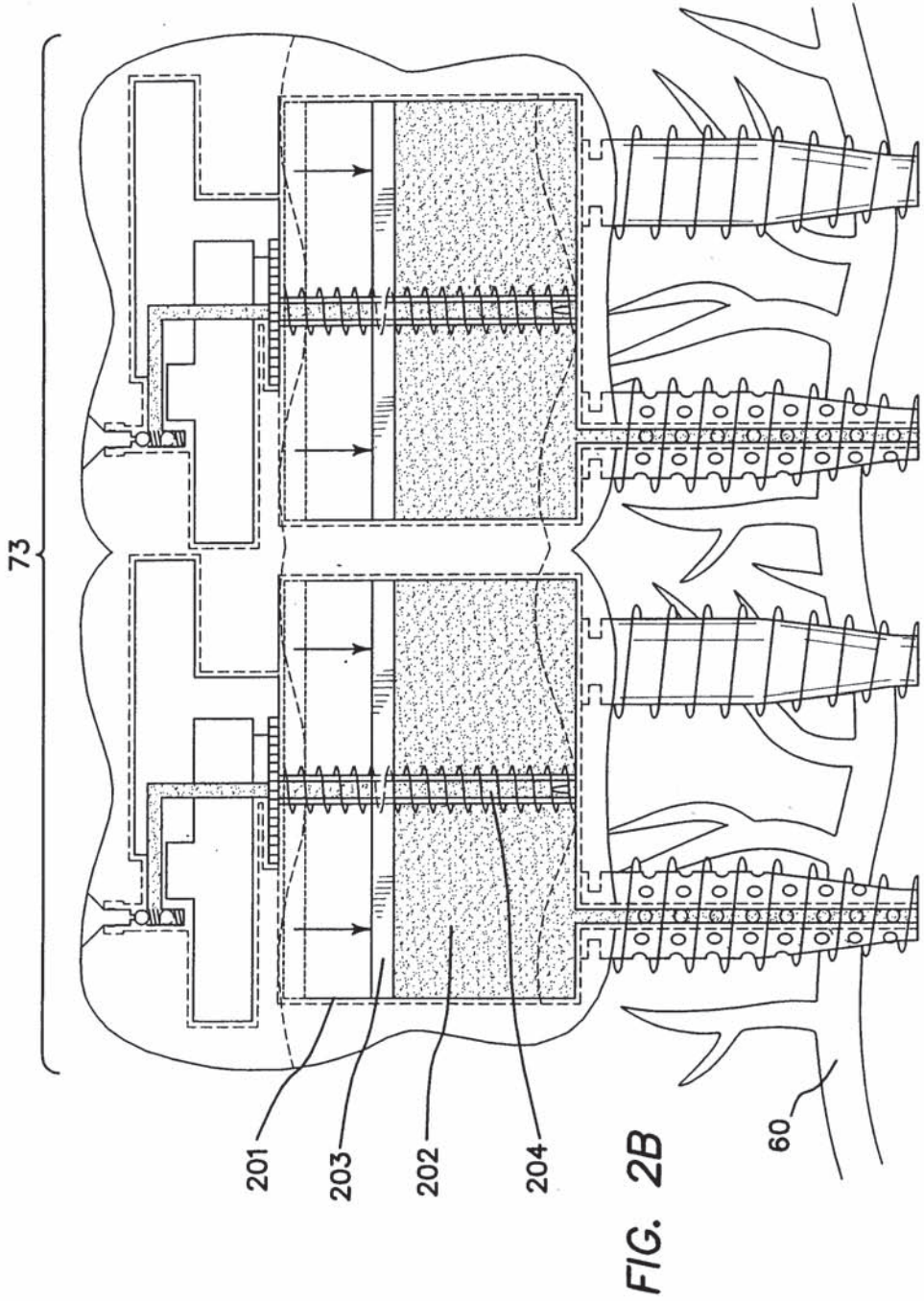
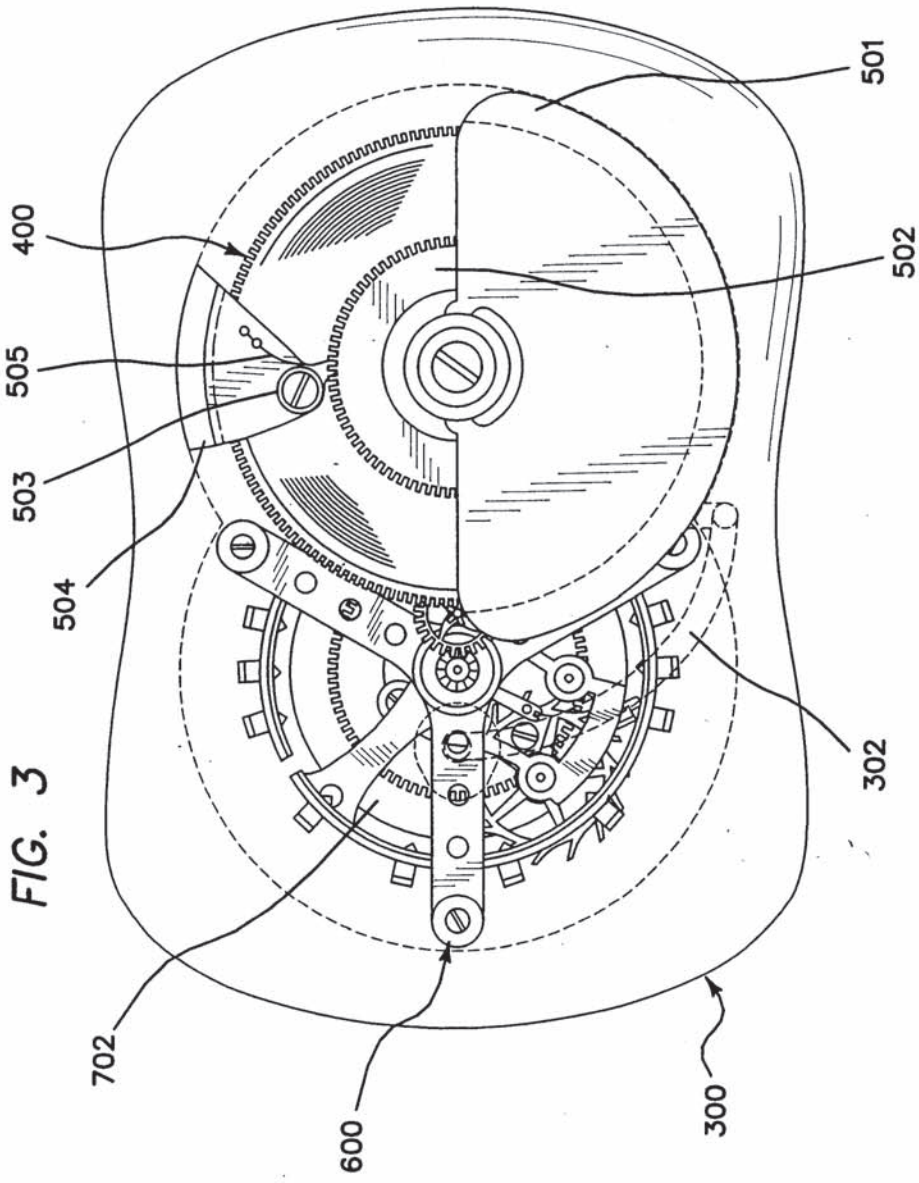


FIG. 7





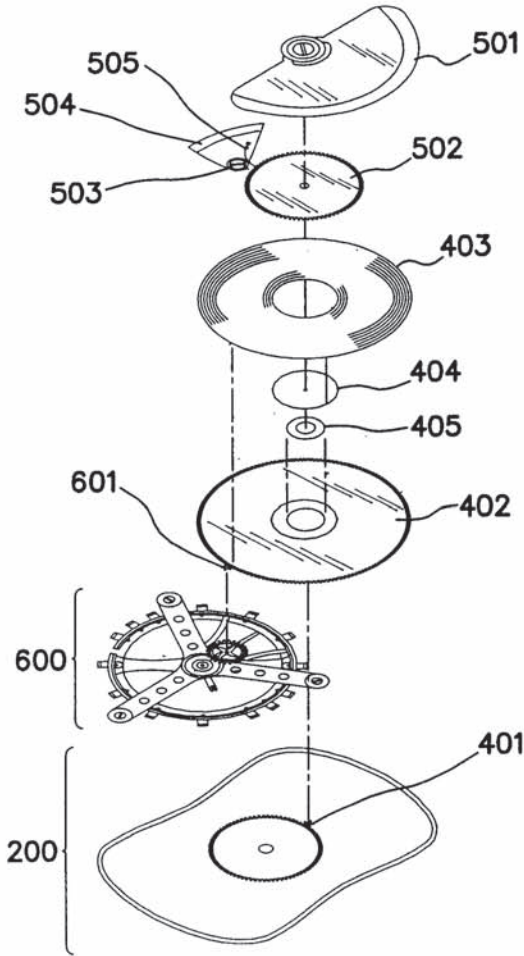


FIG. 3A

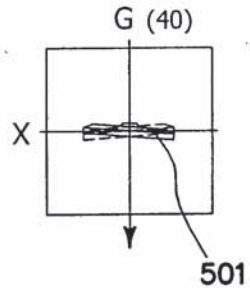
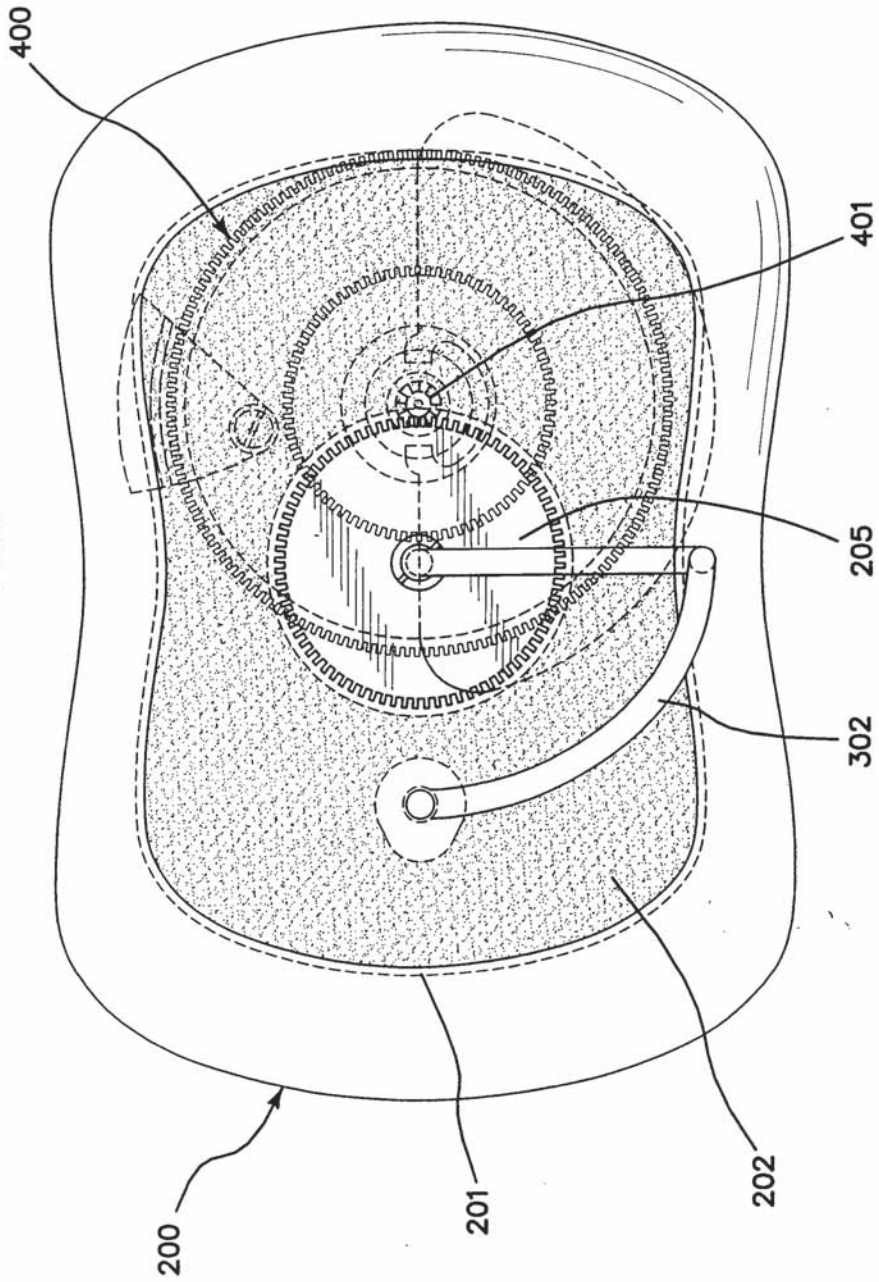


FIG. 3B

FIG. 4



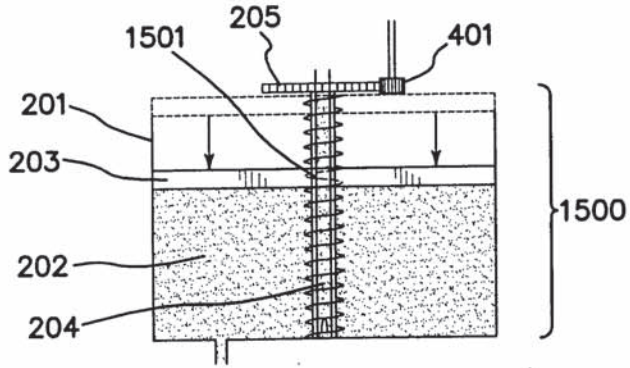


FIG. 4A

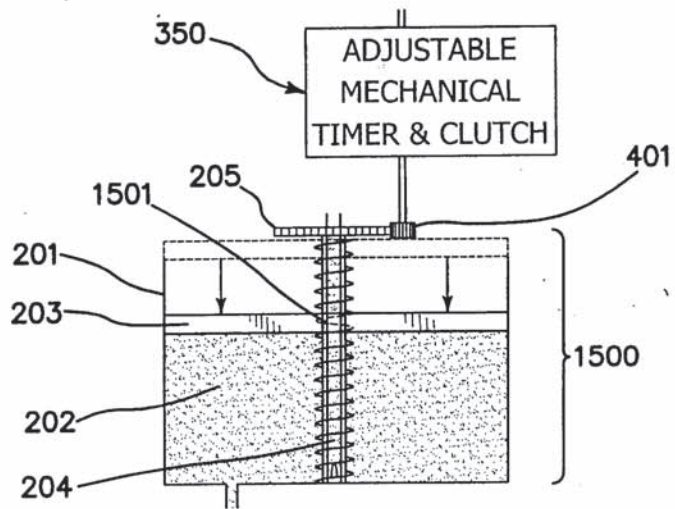


FIG. 4B

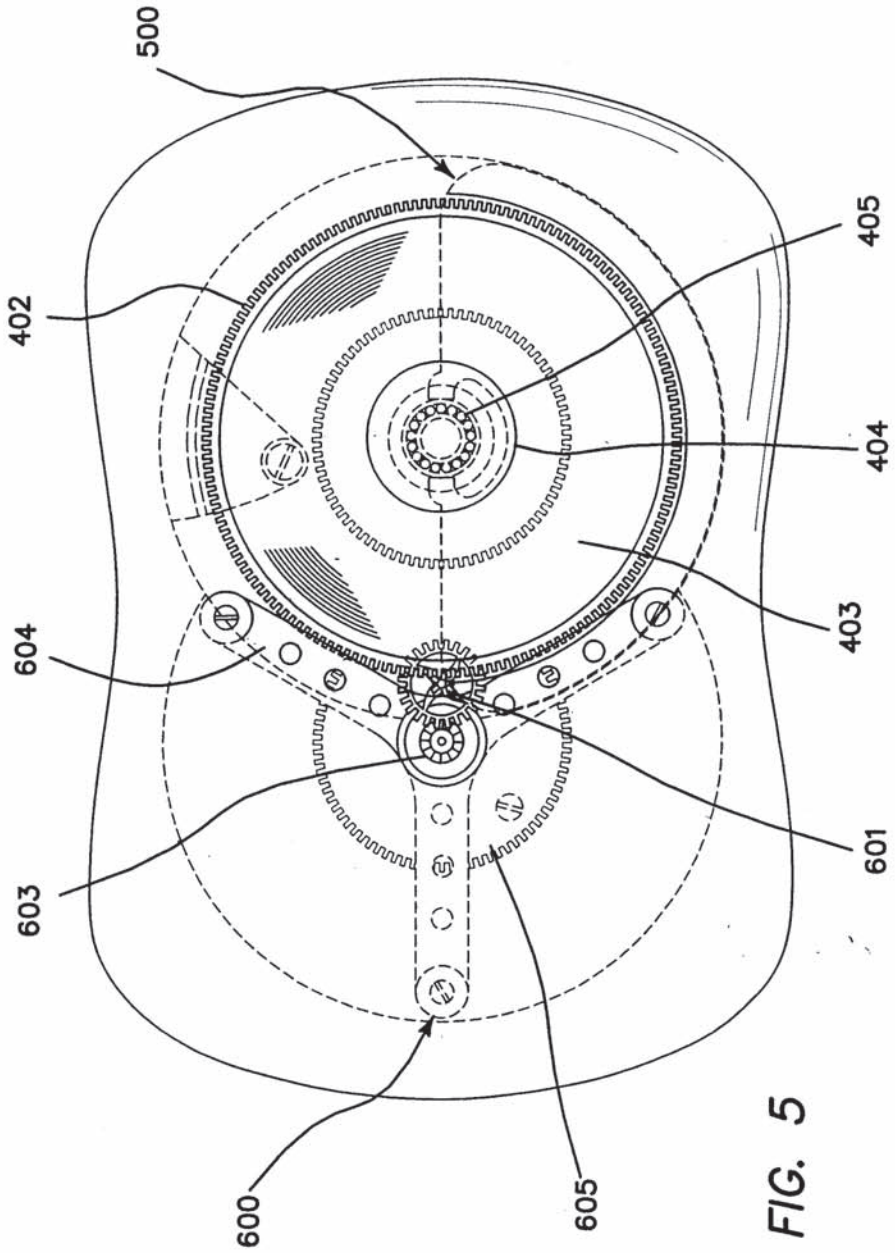


FIG. 5

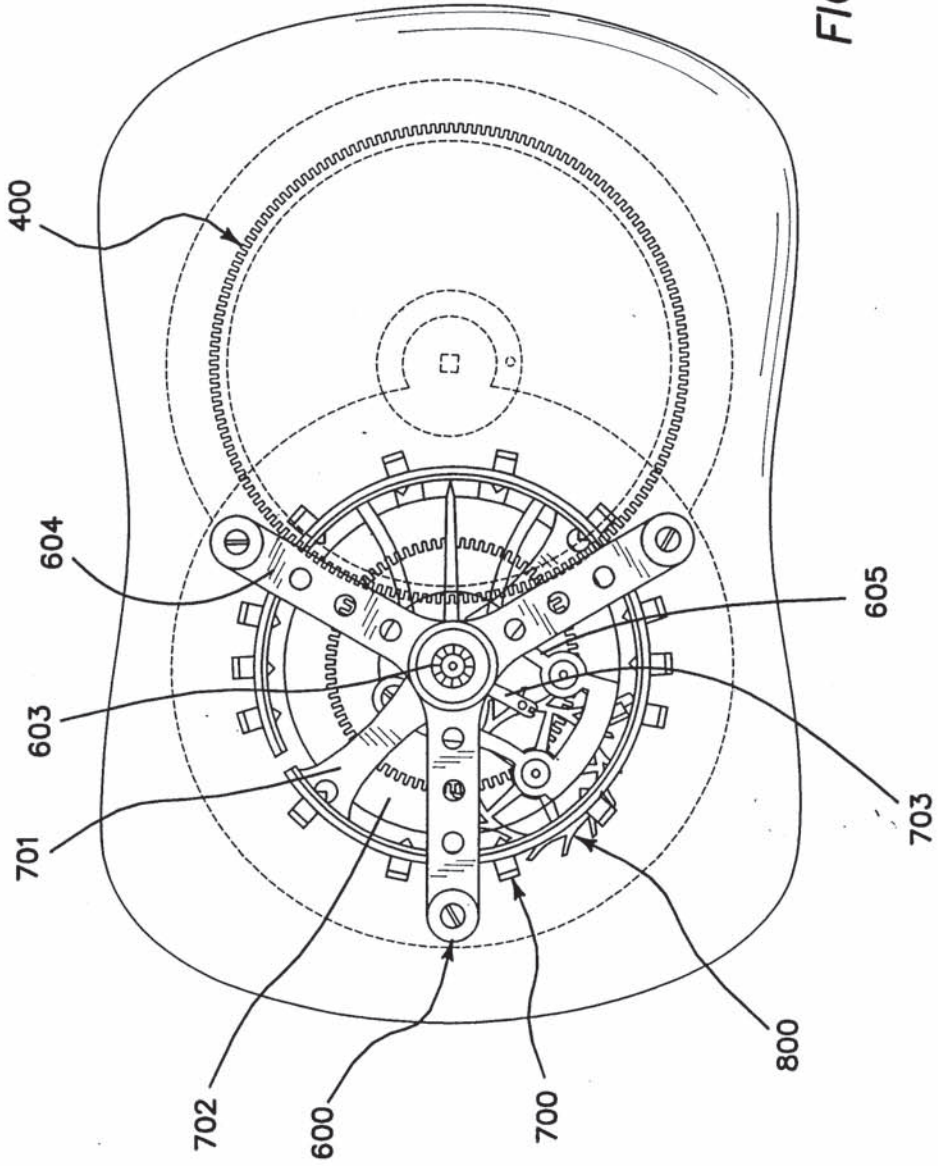
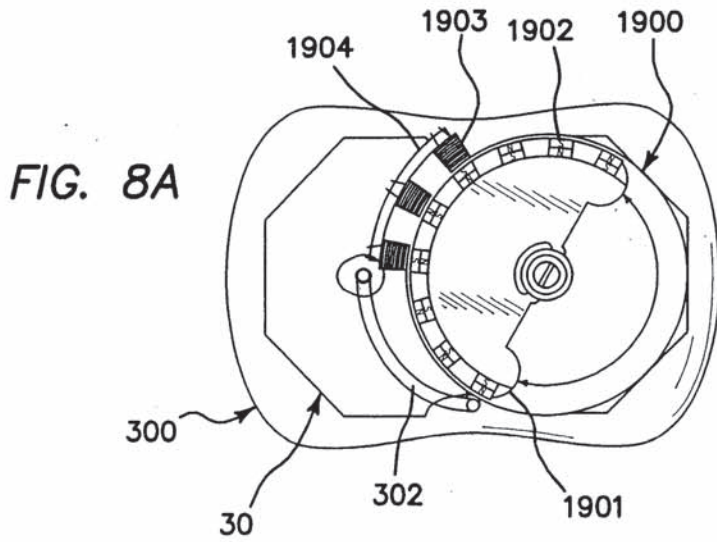
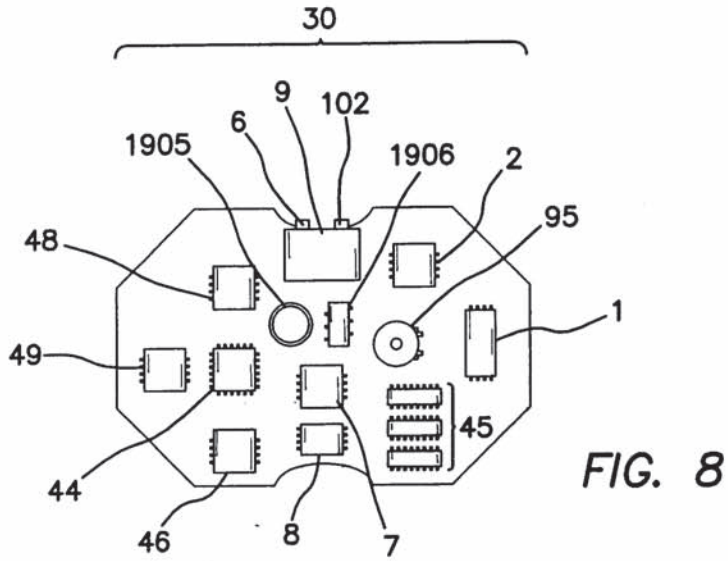


FIG. 6



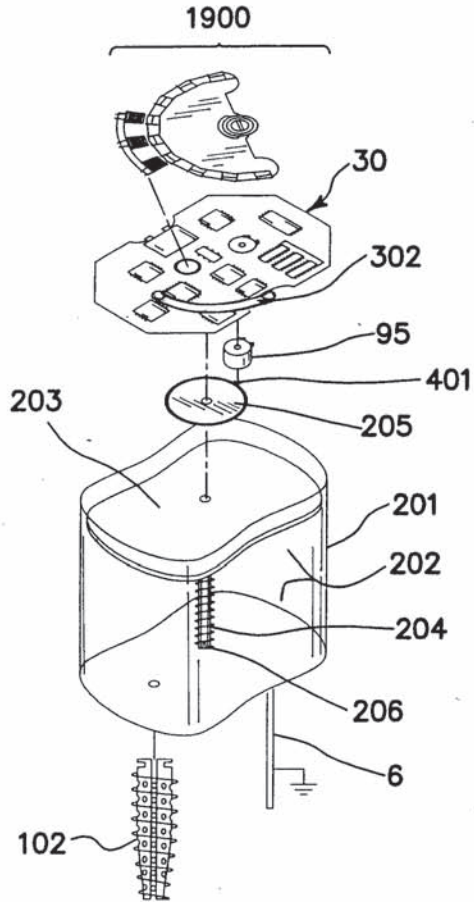


FIG. 8B

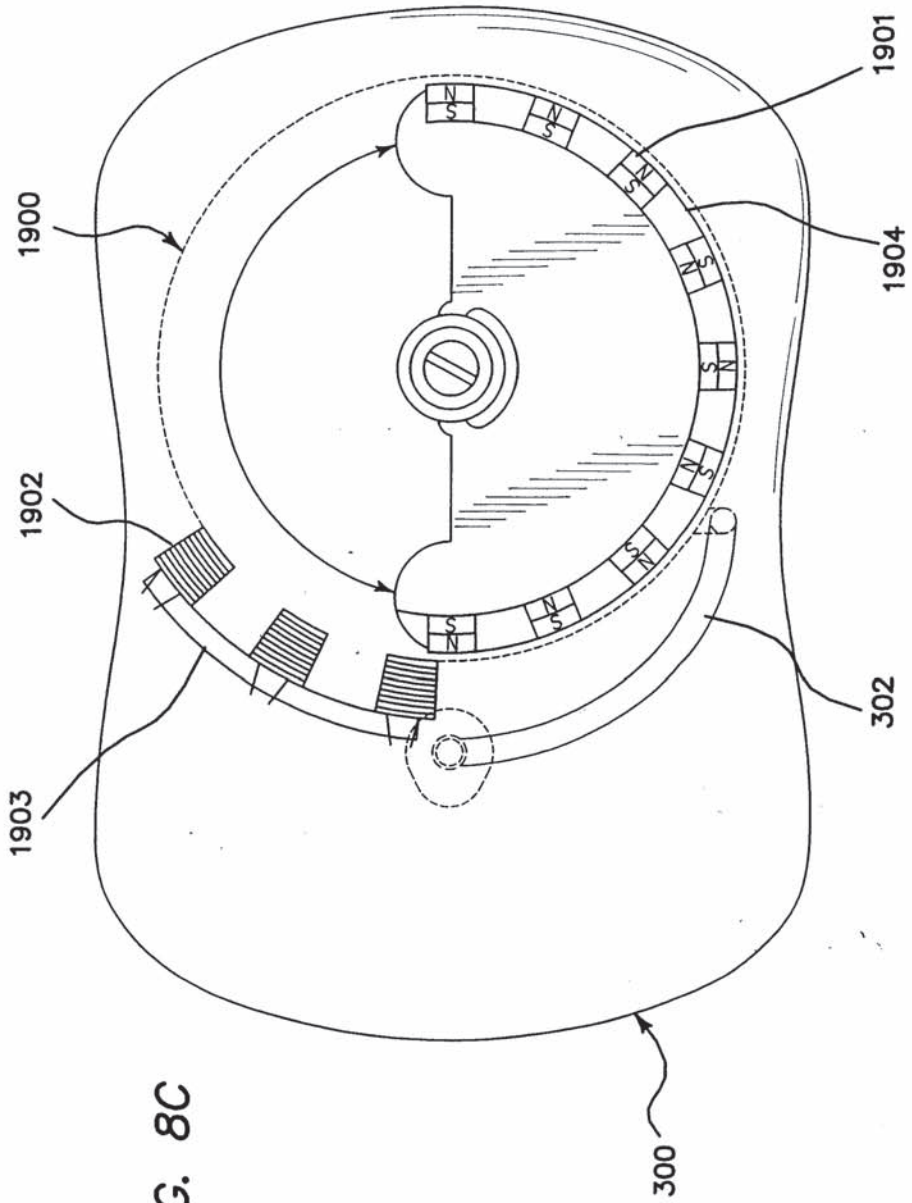


FIG. 8C

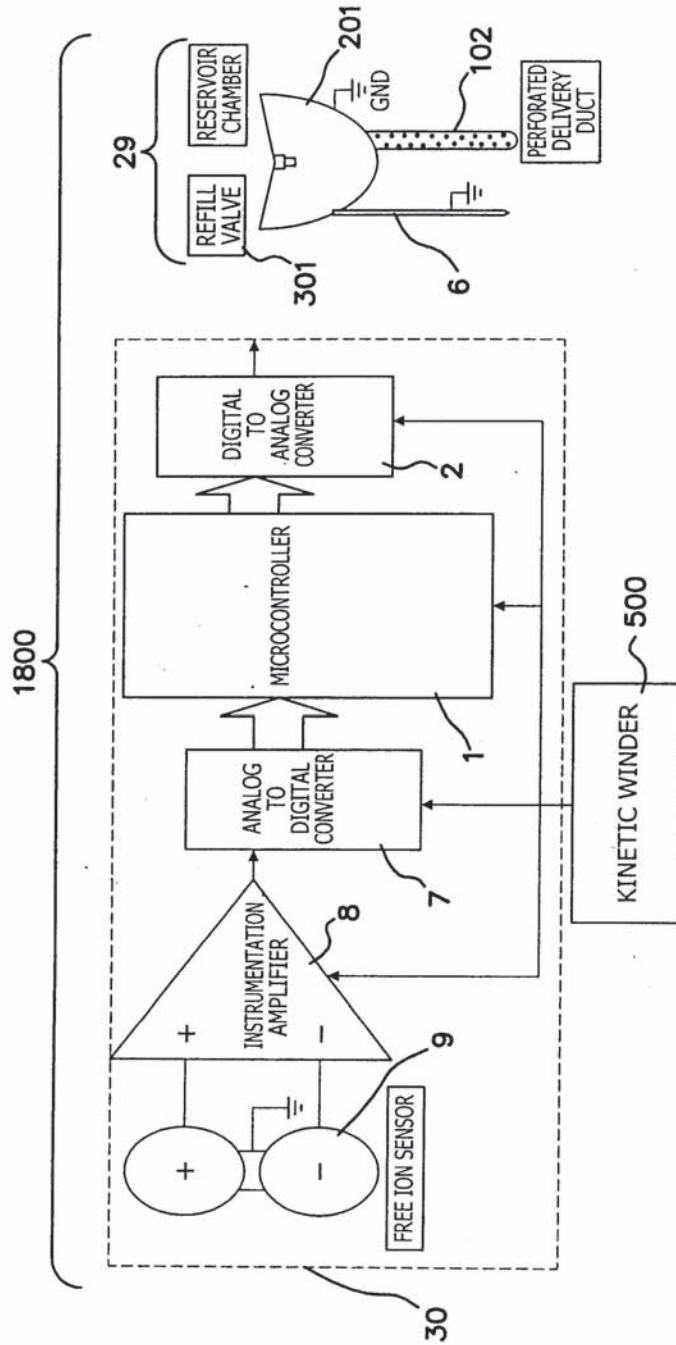


FIG. 8D

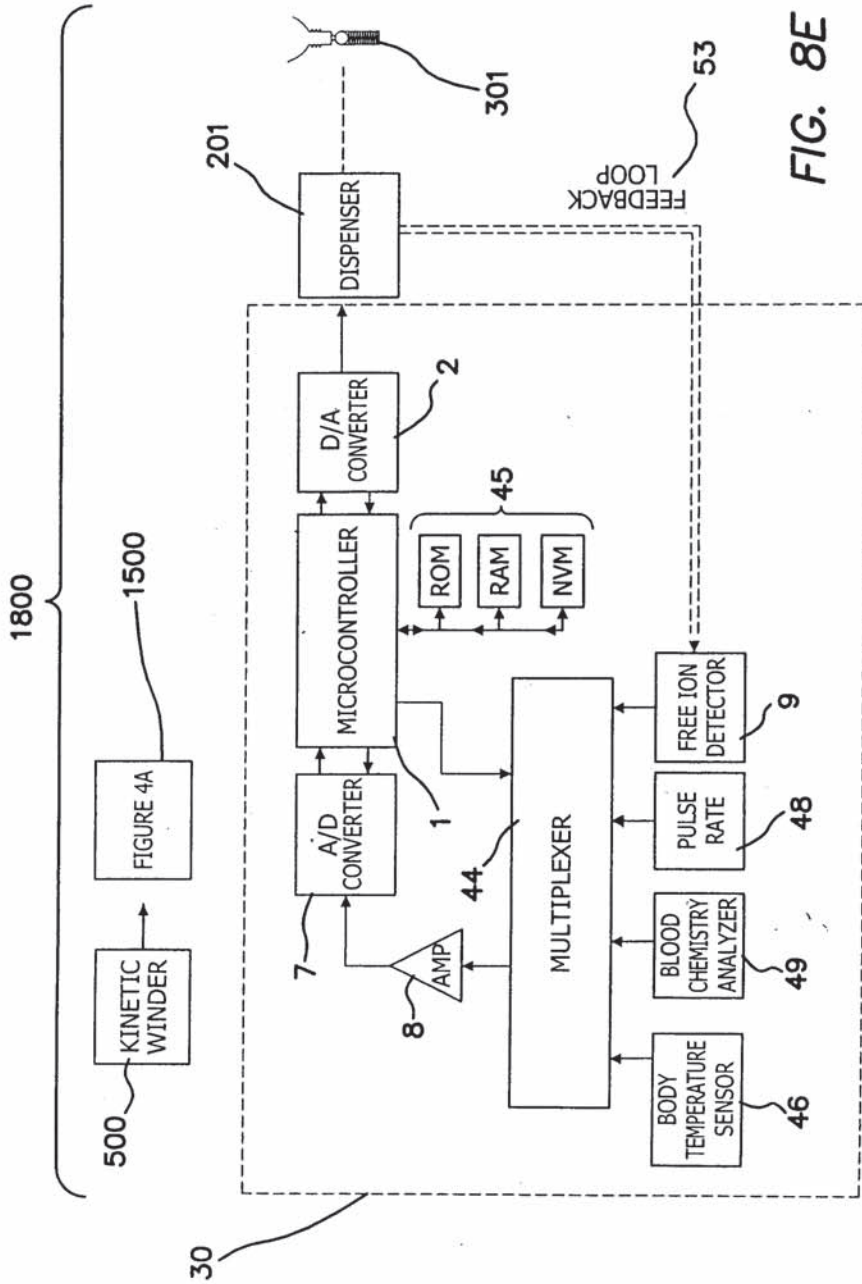


FIG. 8E

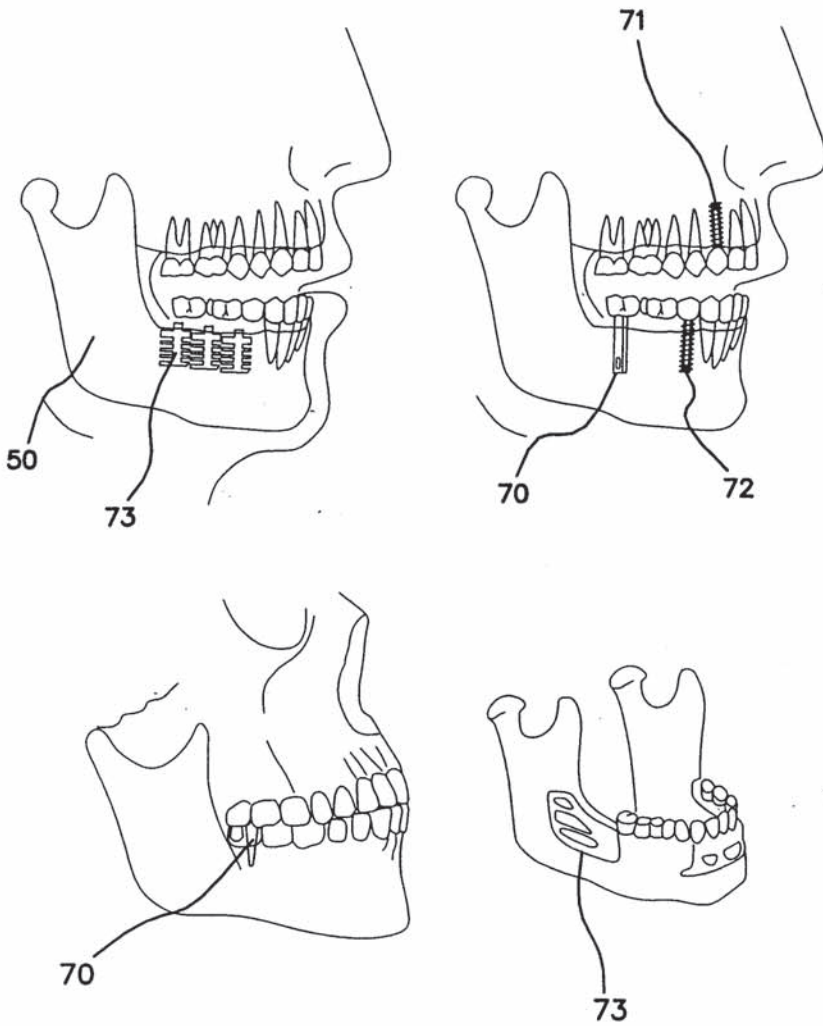


FIG. 9